## Subsystems

A subsystem is any functional part of the robot. On PIMP, these subsystems are:

* Drivetrain
* Lift
* Grabber

### What goes in a subsystem

### Types of Subsystems

Subsystems and PID subsystems

## Commands

Commands are anything you want the robot to do. Anything a button does is a command. Any step in the autonomous mode is a command. Even something like driving with the joysticks is a command

### Command Groups

Some commands are made up of a list of commands. These commands can executed in order (serial) or at the same time (parallel).

## Teleoperated Mode

## Autonomous Mode